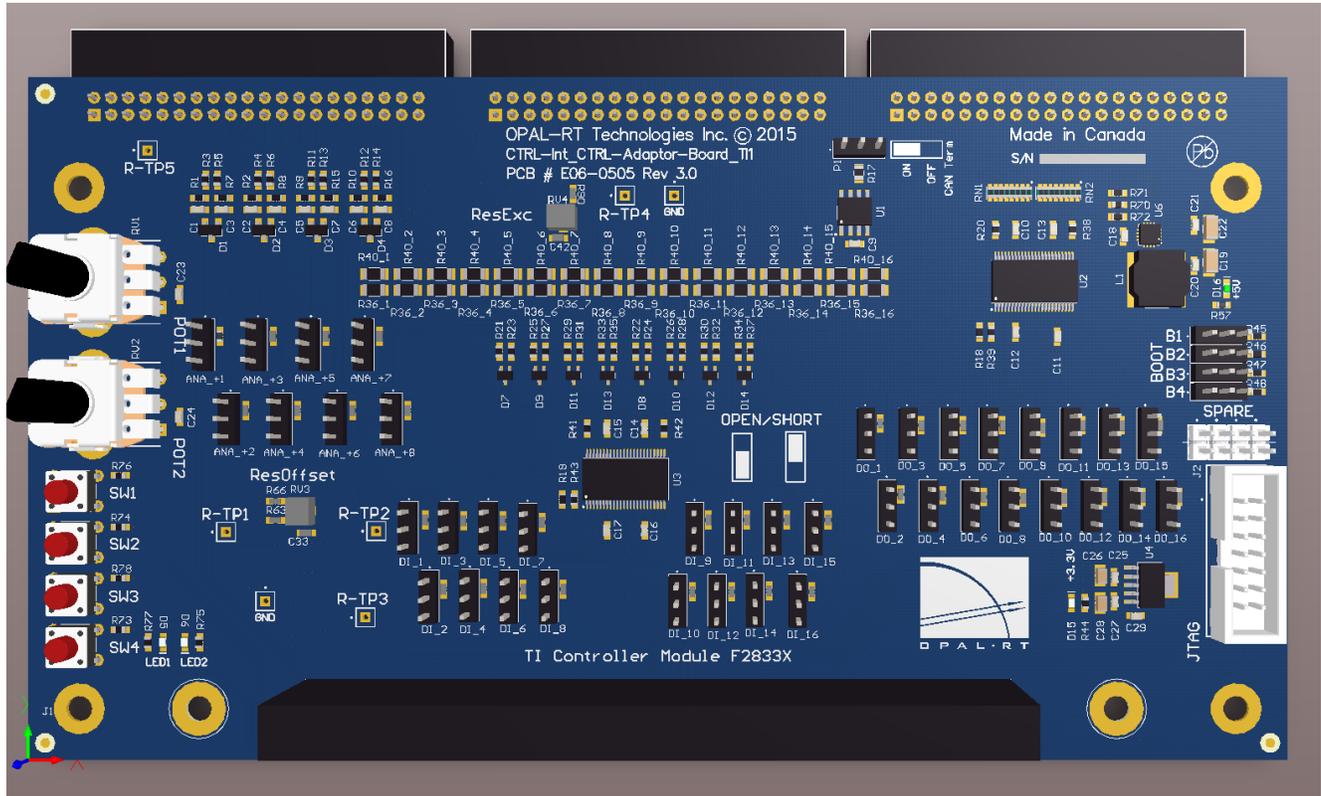


# OP8665 Controller Board Description

- [Controller Board Overview](#)
- [Detailed Features Description](#)

## Controller Board Overview



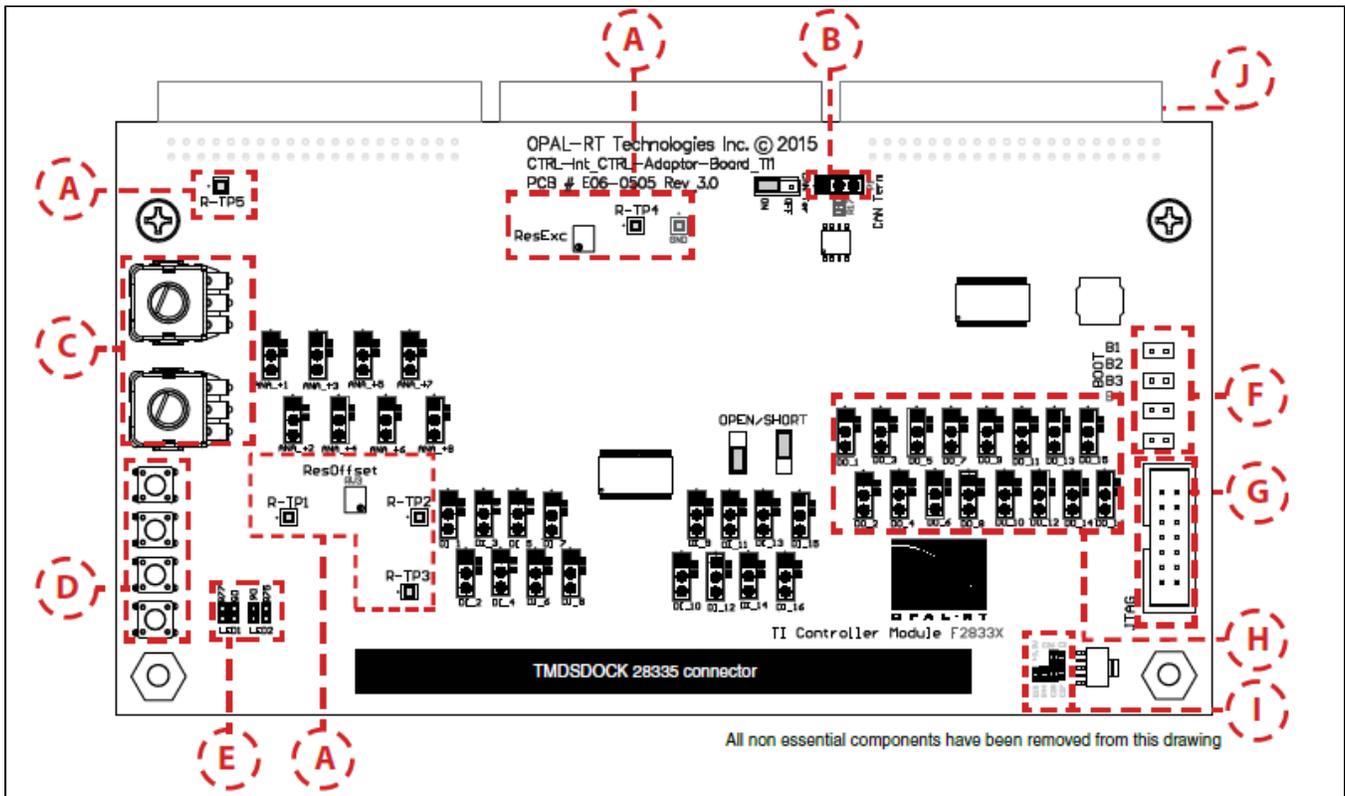
The controller board holds the Texas Instrument DSP module via a 100-pin DIMM interface. It also offers a number of features designed to make using the OP8665 easier and more flexible.

It allows users to scale 0-16V to 0-3.3V. Analog inputs are scaled using the scaling factor  $V_o = V_i * ( 1 / 4.74 )$ , as in this example:

- $V_i = 10V$  (From HIL)
- $10V * ( 1 / 4.74 ) = 2.1097V$  at the TI Controller

The controller board is powered by the controller interface (OP8665) via the 12V input power supply. It is connected to the interface board through three (3) 40-pin connectors.

Switches and potentiometers let users inject stimulus, a JTAG interface provides access for programming and debugging. The controller board also provides input protection.

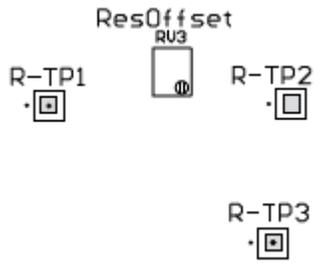
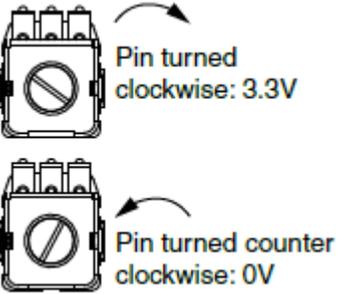
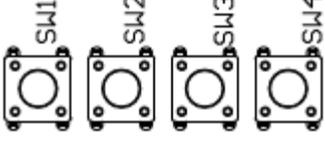
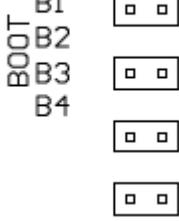


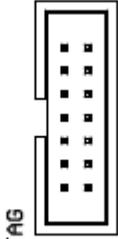
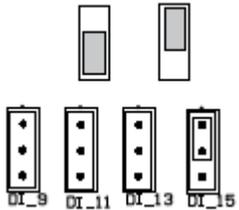
A	Resolver signal calibration potentiometers (3)
B	CAN Jumper, to connect or disconnect the CAN to DSP
C	Potentiometers, to select controller supply of either a 0V to 3.3V input
D	4 push button switches to drive DSP input
E	LEDs displaying DSP output
F	BOOT selector jumpers. For OPAL-RT technicians' use or by engineers familiar with TI controller programming.
G	JTAG connector for programming or debugging
H	36 Jumpers for input/output control resolver signal calibration
I	Power LEDs



ResOffset and ResExc labels are inverted in Version 2.x of 126-0505. Make sure to invert connections as necessary. Failure to do so may result in incorrect results obtained when operating the system.

## Detailed Features Description

<p><b>A: Resolver Offset potentiometer</b></p>	<p>The Controller Board provides a Resolver circuit. The Resolver circuit can be calibrated via two potentiometers and the signals can be probed via test points.</p> <p><b>RV3:</b> used to adjust the Resolver SIN and COS signal offsets. The offset voltage can be measured by probing R-TP1. In general, offset should be adjusted to in-between signal to avoid clipping at the output.</p> <p><b>R-TP1:</b> used to adjust 0.5-3.3V (adjustment in RV3 provides 1.5V on R-TP1).</p> <p><b>R-TP2:</b> used to probe SIN offset value. Amplitude measured at R-TP2 should be between 0.1 V and 2.3V for correct operation.</p> <p><b>R-TP3:</b> used to probe COS offset value. Amplitude measured at R-TP3 should be between 0.1V and 2.3V for correct operation.</p>											
<p><b>A: Resolver Excitation calibration potentiometer</b></p>	<p><b>RV4:</b> used to adjust the resolver excitation signal's voltage amplitude.</p> <p>R-TP4 is used to probe the excitation signal output of the Resolver Circuit.</p> <p>Signal will saturate around <math>\pm 5.5V</math></p>											
<p><b>B: CAN jumper settings</b></p>	<p>Users can add a 120 Ohm resistor simply by placing the CAN jumper in the ON position, as shown.</p>											
<p><b>C: Potentiometer settings</b></p>	<p><b>User potentiometers provide 0V to 3.3V output:</b></p> <ul style="list-style-type: none"> <li>POT1 is used for ADC_A5</li> <li>POT2 is used for ADC_B5</li> </ul>											
<p><b>D: DSP switches</b></p>	<p>The user switches SW1 to SW4. These switches are Normally Open and pulled-up to 3.3V. Press and hold to obtain 0 V (release to return to 3.3 V).</p> <ul style="list-style-type: none"> <li>SW1 – GPIO59</li> <li>SW2 – GPIO58</li> <li>SW3 – GPIO61</li> <li>SW4 – GPIO60</li> </ul>											
<p><b>E: DSP output display LEDs</b></p>	<p>Only ON when the voltage is at 0.</p> <ul style="list-style-type: none"> <li>LED1 -&gt; GPIO62</li> <li>LED2 -&gt; GPIO63</li> </ul>											
<p><b>F: BOOT selector jumpers</b></p>	<p>Selector Jumpers: these jumpers are reserved for OPAL-RT technicians or engineers who are experienced with Texas Instruments controllers.</p> <table border="1" data-bbox="370 1528 587 1738"> <thead> <tr> <th>Jumper ID</th> <th>Signal</th> </tr> </thead> <tbody> <tr> <td>B1</td> <td>GPIO84</td> </tr> <tr> <td>B2</td> <td>GPIO85</td> </tr> <tr> <td>B3</td> <td>GPIO86</td> </tr> <tr> <td>B4</td> <td>GPIO87</td> </tr> </tbody> </table>	Jumper ID	Signal	B1	GPIO84	B2	GPIO85	B3	GPIO86	B4	GPIO87	
Jumper ID	Signal											
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<b>G: JTAG connector</b>	<p>Allows the user to debug/flash the TI controller.</p> <table border="1" data-bbox="363 176 678 470"> <thead> <tr> <th>Signal</th> <th>Pin</th> <th>Signal</th> <th>Pin</th> </tr> </thead> <tbody> <tr> <td>TMS</td> <td>1</td> <td>TRSTN</td> <td>2</td> </tr> <tr> <td>TDI</td> <td>3</td> <td>GND</td> <td>4</td> </tr> <tr> <td>NC</td> <td>5</td> <td>NC</td> <td>6</td> </tr> <tr> <td>TDO</td> <td>7</td> <td>GND</td> <td>8</td> </tr> <tr> <td>TCK</td> <td>9</td> <td>GND</td> <td>10</td> </tr> <tr> <td>TCK</td> <td>11</td> <td>GND</td> <td>12</td> </tr> <tr> <td>EMU0</td> <td>13</td> <td>EMU1</td> <td>14</td> </tr> </tbody> </table>	Signal	Pin	Signal	Pin	TMS	1	TRSTN	2	TDI	3	GND	4	NC	5	NC	6	TDO	7	GND	8	TCK	9	GND	10	TCK	11	GND	12	EMU0	13	EMU1	14	 <p>JTAG</p>
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<b>H: Input/output jumpers</b>	<p>Jumpers allow users to insert a short or leave the circuit open, as needed.</p> <p>Each jumper controls a specific channel, identified at each jumper on the board (see image opposite).</p>	<p>OPEN/SHORT</p> 																																
<b>I: Power LEDs</b>	<p>Green when 3.3V power is functioning</p>																																	